Do not downgrade firmware that was installed by the manufacturer! You may get a brick

Each device has its own firmware and is updated separately from different menus. It does not matter in what order you update the firmware of the devices. If you have older firmware, you can install the latest firmware at once, without having to install the firmware one by one.

If you already have firmware version **v0.75B** and higher installed in the On-board computer, then the order in which devices are updated does not matter, since in firmware **v0.75B** the ability to force the update of the controller and other devices connected to the CAN bus through the menu of the On-board computer was added. You can read more about **Forced update of devices** in this section.

If your On-board computer has firmware **v0.60B** or lower and Controller **v.7.18** and lower, first, need to update all devices but display. Because menu protocol is new and old devices will not be visible in the menu. After the update is finished hold the left button few seconds to exit the updated device menu. If the button does not work you may need to reset the power supply or replug CAN cable in the On-board computer. After everything is updated — update the On-board computer. Make a controller reset (load defaults) after the update. We recommend running motor detects again on controllers. Detection of throttle/brake connected to display should be done in the On-board computer menu.

Copy files to the root directory of the microSD card with FAT32 filesystem (how to format microSD to FAT32 on Windows and Mac you can read here), insert into On-board computer (contacts on top) and run the update process.

Instruction of update of firmware:
1. Description of the On-Board Computer update menu.
2. Description of the Controller update menu.
3. Description of the uLight update menu.

To check the current firmware version, go to the **Device Information** menu, each device has a separate menu.
1. Information about the firmware version of the On-Board Computer.
2. Information about the firmware version of the Controller.
3. Information about the firmware version of the uLight.

The list of actual firmware to be downloaded:

2 Feb 2024

uLight v0.6.8
LEVCAN updated.
Added brake 'Brk' to button inputs for functions.
Removed reverse when CAN buttons active.

2 Feb 2024

uLight v0.6.6
LEVCAN updated.
Added to functions 4 configurable signals with button input.
Added configurable logic: AND, NOT, OR, XOR, as another button type.

22 Dec 2023

uLight v0.6.5
Small update:
Added brake button selection for only light indication without actual braking.

30 September 2023

Recommended to update display first! Export configurations before update and import after to save your settings.

Controller v0.8.13

Added reset handlers
Added quick battery voltage setup
Fixed dc-dc mode for P24F
Added LR detect indication
Throttle/brake error replaced with 'not connected'
Added temperature sensor detect logic when sensor disabled
Added access level selection
Added boost mode duration
Fixed active braking stutter
Adjusted square control duty cycle

Display v0.82B

Added access level menu support
Fixed some freezes
Fixed displayed mode with multiple motors

21 July 2023

Controller v0.8.12

Added MPPT solar logic
Added throttle lock when brake pressed
Fixed FOC 'square' noise
The added neutral mode by timer
The button now turns off without the need to release it
Active braking fix when not enabled (stutter fix too?)
Added motor gear ratio
Speed kp changed the default to 0.1
Added separate throttle mode power+torque
Fixed storage erase when both banks are full
Increased ampere offset at startup for plate
Added power indication in the Converter menu
Small parameter text fixes
Added continuous logging mode
Temperature calculation moved to a separate file
Current calibration now only saved when the test finished
Added error when current calibration out of range
Battery min charge current can be set to 0 now
Added NTC10k3500
Added file flush when log rate slow
Added ADC sample timetable
Logger settings offset calculated automatically
FOC ADC current sample for P24F changed from ADC3 to ADC1+2
Remove low speed for changing HZ mode
Added cruise-ready flag
Added throttle lock when brake pressed
Added low ripple PWM mode (for FOC)
DMA removed, because of triple buffering (noise fix)
Added throttle-locked flag
SVM sector selection moved to a separate function
Added lock flags index by function name
Increased default throttle response
Advanced modes now have default throttle = torque

1 July 2023

uLight v0.6.4

Added export/import
Added kty84 tsensor

Added hazard switch logic, works when everything is off
Added brake strobe effect
Added data that can be requested over LEVCAN

7 May 2023

Controller v0.8.11

v0.8.10:
Added Adaptive throttle mode (by default with 6%)
Added Power throttle mode
Added PAS scaling with buttons
Added Torque sensor minimal pressure for insta-start
Forwarded hall error to display flag
Changed hall error detection logic
DC-DC now shows current on each phase
Added TF21904M potential driver fix
PhaseResponse added phase selection
Updated flag names for sensor errors
Added phase currents and voltages for LR detect
Added PAS voltage filter
Added PAS voltage selection (throttle or vpas)
Added new inputs (I1-I13)
Inputs renamed
Added checks to HWPort HAL
Added t-sensor resistance compensation
Added DAC current protection temperature correction, needs optimization
Added 5V for FW
VBUS calculation moved to RAM
Added FreeRTOS-gcc workaround
R detection now uses 50% pwm as offset
New timer sync method for upcounter mode (R detect)
Motor LR auto detect enabled
Added AN brake input 'switch' detect by dV
Added MTPA enable detect when inductance is 30% bigger
Added hall input filter
Added hall step forward filter with min step time
Added fallthrough directives
Added parameters size check as warning
Fixed inputs array position
Motor LR moved to the last detection position
Added local port input filter
Added Enable Throttle function (opposite to Disable Throttle)
Added Hall sensor minimal step time
Added wait code for R detect
Fixed voltage error on R detect
Fixed negative flux linkage

Disabled MTPA, FW, and other options for hall calibration
Added Adaptive throttle to adv. modes
Control structure optimized
FOC FW improved, should not stuck
Vq limit removed, now it is by default
Added (by default) MTPA mode by real Q current
Small FOC optimizations
Added TIM1 as a variable to linker script
Hall code moved to upcounter while FOC in down-counter (buzz fix #1)
DMA is now in circular mode, it needs less code with same effect.
Added noise suppression in vq vd to decrease sector change (buzz fix #2)
Storage updated, improved reliability, and now with version system
Fixed invisible fault flag in logger
Updated logger defaults
v0.8.11:
Small optimizations
Logger FOC parameters replaced to filtered values in fast mode
Data Storage unit-test updated
Fixed a few bugs in Data Storage
LEVCAN updated with recent bugfixes
Added additional tests for Data Storage
Startup junk removed
Logger fixed hang-on display disconnect
Logger cache moved to SRAM2
FOC pids rolled back to v0.8.9
Speed max increased to 200%

Display v0.80B

Changed voltage drop saving
Fixes in LEVCAN
Fixes in flash saving
Fixed RPM in info lines
v0.80B: Data Storage updated with latest fixes

8 Febrary 2023

Controller v0.8.9

You will need to run new motor detection after update!
This update fixes issues with the reverse function of the previous release and also some problems with recently made controllers. There are known issues with starting under high currents that will be investigated later.

Added interrupt setup logic.
Added High V ripple flag for plate controller.

Added middle DAC offset from raw ampere calibration.
Fixed EXTI-PR register reset in the main logger.
Fixed Neutral for the master controller.
DAC offset updated for the plate.
Fixed square wave plate reverse.
Fixed reverse sensorless startup logic.
Added hall idle parameter.
Hall angle fixed, now transition with offset, when not interpolated — no offset.
Added fix in HW config for TF21904 drivers (shipped after Dec 2022 till Feb 2023).
Added fault flag to the logger.
FOC has removed the extra current at the start.
FOC angle now has no offsets.
FOC sectors moved to match the square wave.
FOC added an additional dead time gap.
Added load defaults by section.

14 October 2022

Display v0.75B 
Export configuration before the update, update the Display, and then import your config!
Added menu for forced device update.

- Added passwords for devices menu and main menu.
Configurable max visible speed in statistics.
Fixed some SD card issues, and added exFAT support (not for display update).
Added phase current bar min/max setting.
Added menu for forced device update.
Fixed brake voltage inversion.
Fixed Wh calculator for high power.
Removed info line scroll in info line theme.
Phase current now showed as Ap.

26 September 2022

Controller v0.8.8 
Export configuration before the update, update controller, load default settings, and then import your config!

Added motor angle to logger
Fixed errors in combined transition logic
Fixed clutch negative current spike
Added FOC vq limit parameter for QS165 motor
Fixed reverse operation for vq limit
Current calibration fix for shunt

Levcan got an update on ParseParameterValue
Fixed PWM minimum time for TF driver (FOC)
DAC constant updated with calibrated value
Position sensor temporary fix for FOC when not interpolated
Added remote throttle timeout (locked screen full throttle bug)
Many small fixes for assembly testing

8 August 2022

Controller v0.8.7 

Fixed sensor logic for square wave
Fixed adc issues but still should be improved
ADC logic changed to more future-proof
Added configuration import with button
Added import lock when motor spinning
Moved PLLs to separate file
Fixed current spike on brake press (filter abs duty)
Removed 'hall invalid' logic from interpolation start
Improved speed control for reverse from forward movement
Position sensor logic separated
USB code deleted
Stop PWM on debug added to pwm hal
SQ have sensorless interpolation
Interpolation logic improved
Deleted global PositionSensor variables
Fixed speed reference NaN
Added diagnostic mode to state machine switch
Fixed few diagnostic issues
Live hall angle update in menu
Added NaN checks for hall
Adjusted detected angle for first step
BEMF now have one extra step to skip spike, in case if it falls slowly
Detection sensor state fixed, caused motor to stall
Added frequency startup logic for sensorless square wave (yay!)
Frequency control used for sensorless startup now, default changed to 2
Added encoder position sensor
Pullup control removed
Added encoder menu
Added encoder detection
Updated position sensor logic, detection routed through it
Added hall detect quick fail
Swapped hall inputs to match timer index
Speed calculation changed
Rads calculation moved to Position sensor file
ERPS counter upgraded with direction filter
Encoder angle calibration added

RCPWM disable-exit added
Added pwm port assignment to encoder
Torq sensor exit added
ADC ports reassigned
Few parameters live update fixed
Added encoder info to device info menu
Added E suffix for Encoder
OV and UV flags separated
Test bench code moved to separate file
Includes optimised everywhere
Square wave current offset disabled on next step now
FW added better enable logic, to help avoid extreme brake power on FW
Added few FOC optimisations
Added FOC vq limit before vd-vq vector limit, to let vd do field weakening more (unlimited vq caused worse FW perfomance and sometimes it was stuck)
SQ added DC current dead time compensation
Added out of control detection logic
Added serial number
Added calibration constants
Added calibration logic when checking hardware
Added FreeRTOS stack monitor
Optimised testing procedure for faster test
Updated critical task enter routines
Fixed field weakening integral kick if foc is forced shutdown
Changed PWM Freq to constant
Position sensor menu updated
Over-Field weakening flag logic fixed
Fixed PAS menu parameter update
Moved foc square-boost to sector switch logic
Added PLL low speed smoother logic

6 April 2022

uLight v0.6.3 
Fixed T1/T2 settings menu.
Now possible to disable the turn signal blinking by setting 0 sec.

23 March 2022

Controller v0.8.6 

Field Weakening PID updated.
Added FW limit based on motor temp limit.
Decreased allowed FW vector size to 80%.

Config defaults decreased.
Added locks 10 seconds on temperature exceeding.
Small menu changes and export fixes.

20 January 2022

Critical update for new controllers and hotfix for controllers 6F/12F and old 24F. Export config before the update, load defaults after the update, and import your config.

Important!
If your On-board computer has firmware **v0.60B** or lower and Controller **v.7.18** and lower, first, need to update all devices but display. Because menu protocol is new and old devices will not be visible in the menu. After the update is finished hold the left button few seconds to exit the updated device menu. If the button does not work you may need to reset the power supply or replug CAN cable in the On-board computer. After everything is updated — update the On-board computer. Make a controller reset (load defaults) after the update. We recommend running motor detects again on controllers. Detection of throttle/brake connected to display should be done in the On-board computer menu.

Controller v0.8.5 

Save system updated, added unit tests.
Added clutch shutdown when brake pressed.
Added option to enable MTPA.
USB for computers disabled by default, will be removed in the future Fixed P1 P2 PWM mode.
Lifetime temperature now calculates only when motor powered.
Added hall pullup disable option.
Various save system fixes.
Fixed NaN for resistance detection.
Fixed import of 1st parameter in every section.

Hotfix for 6F/12F and old 24F.

18 October 2021

First, need to update all devices but display. Because menu protocol is new and old devices will not be visible in the menu. After the update is finished hold the left button few seconds to exit the updated device menu. If the button does not work you may need to reset the power supply or replug CAN cable in the On-board computer. After everything is updated — update the On-board computer. Make a controller reset (load defaults) after the update. We recommend running motor detects again on controllers. Detection of throttle/brake connected to display should be done in the On-board computer menu.

Display v0.71B 

Menu redesigned.
All display settings moved to separate menu.
Added port input state in port settings.
Added port functions: disable backlight, lock screen.
Added separate hotkeys while charging.
Added option to use hotkeys with a short click.
Added throttle/brake settings which are connected to display.
Added global odometer setting.
Global stats reset will not reset odometer now.
Added parameters import/export.
Added icons on the main screen (brake, brake limit, turtle mode, motor/controller fault, battery fault).
With new controllers update speed is 6 times faster now.
Logger speed should work faster too.
Added text scroll in the menu.
Logo updated.
Added more informative messages for resets with a password request.
Added parameters that could be requested from display on CAN bus.\\</WRAP> === v0.71
Fixed some parameter editing.
Updated import/export.
Odometer now can be imported, value is not decimal now.
Fixed button blinking while typing a password.
Fixed charge screen, button blinking fixed.
Fixed info-lines names.
Fixed header for password message.

Controller v0.8.2

Added glitchy USB to controller (needs a USB cable connected to PWM port).
Completely new LEVCAN parameters protocol with more possibilities.
Added trip statistics menu to controller:
-Wh regen/used/total.
-Ah regen/used/total.
-Estimated motor efficiency realtime and average.
-Calculated motor torque (on shaft).
Temperature measurement now calculates t-sensor resistance.
Improved kV detection.
Fixed 'bug' with long brake response on slow current change speed for acceleration limit.
Defaults for all ports now OFF.
Added brake button % (percentage of brake phase current for button-brake).
Added brake on released throttle (brake phase current).
Motor inductance and resistance detection for MTPA.
MTPA logic (works good only with IPM motors).
Fixed FOC FW to be triggered at stop when braking.
Added more control CAN commands.
Added more parameters that could be requested from controller on CAN bus.
Added more logger parameters.
Added hall filter settings to debug stuttering.
Added prefix selection for controller name.

=== v0.8.2
Added log header option.
Added translation for some messages (RU).
Added error messages for throttle/brake detection.

uLight v0.6.1

New LEVCAN parameters protocol.
Fixed PWM IO settings, now they do work.
Added temperature sensor thresholds, they work as virtual button for functions.
Added ability to send button inputs to CAN bus.
Main program source code published on GitHub:
https://github.com/Nucular-tech/uLight

31 August 2020

Use configuration export before update, reset defaults after update and import configuration.

Display v0.60B

Fixed throttle drop.
Small menu fixes.
LEVCAN updated.
Button setup simplified, by default all set to CAN mode.
Added exFAT support (but display still can be updated only from FAT32).
Added charge screen.
Added fast statistics type selection.
Added wider event window.
Mph stats fixed.

Controller v0.7.18

Experimental logger added.
Fixed many charger glitches, however still have few.
Added soft start to charger and more safe phase detect.
Completely reworked field weakening, now should not have any hard braking after release.
Added minimum speed reference for speed PID.
Added RC PWM control on P1 port (throttle/brake).
Added more logger parameters.
Few important FOC control fixes, DC current should be calculated better under field weakening.
Fixed one weird ultra-rare bug in square mode.
LEVCAN operates on queues now, log time 2x faster when display updated.
Decreased DCi Ki default from 500 to 200.

Slightly decreased FW start point.
Added full debug info export.
Added logger mode selection and tuned logger start.
Removed first line from log for easy datazap upload.
Throttle / brake curves added (8 point configuration) with presets.
PAS extra scale added for additional modes.
Soft acceleration for cruise added, more shutdown triggers.
Cruise logic updated - phase current limited by selected mode, not throttle position.
Minimum cruise speed - limits cruise activation.
Cruise increment/decrement - control cruise speed with buttons (port = CR+/CR-)
Cruise restore - recovery last saved cruise speed with button, activated only above min cruise speed. (port = CRr)
Power limit added to modes and battery configuration. 0 = power limit disabled.
Small menu fixes.
CAN inputs increased to 16.
Parameters export / import fixes.
12V shutdown fix.

18 March 2020

Display v0.59B
HOTFIX for display speed sensor

11 March 2020

Display v0.58B

Fixed 0V throttle issue.
Fixed charge statistics reset.
Added kmh/mph switch.
Added more parameters to info. lines on main screen.
Added hotkey mode for compatibility with controller speed functions.
Fixed contrast setting.
Added driving range, calculated from WH usage.
A lot of tiny fixes.

Controller v0.7.12

Torque PAS fixes
Fixed configuration import for advanced modes
Added configuration selector from 1 to 9
Import will show first line of configuration, you can put a comment here

Fixed N mode
Fixed motor wiggle at charger mode
Added more debug information

21 Nov 2019

HOTFIX, fixed NaN error for analog inputs.

Controller v0.7.9

20 Nov 2019

Export configuration (or make screenshots), after controller update do “Erase data storage” and reboot. Configuration will not be imported fully, some values will need to enter manually.

Display v0.57B

CAN buttons setup
Inverted inputs setup
Statistics reworked
Added filters for analog inputs

Controller v0.7.8

Big menu update
Control logic completely reworked for future compatibility with BMS
New default values for PIDs
DC-DC low voltage difference charge fixed
Inverted brake input added
Specific setup for 3 positional speed switch added (can work now as 1-2-3)
Button/switch select for usual speed select input
Save CRC calculation fixed
New speed mode - neutral
Speed increment and decrement added
Added t-sensor NTC 10k B:3380
Reboot command added
Fixed field weakening over 126%
Fixed VBUS measuring, now it is at PWM frequency, significantly improved overvoltage protection
Added median VBUS filter
Added averaging of N-X ADC samples filter for throttle and brake
Fixed brake glitches
Current measuring fixes for better measuring on 6F board
When enable button configured controller will not turn-on anymore when power applied
Autodetect improved, more informative, short-circuit detect added and timeout fixed

Added lock-at-turn-on, will lock throttle untill password on-screen is entered
Voltage on phases detect added, will lock controls
UVLO added
Added “Advanced modes” menu with more specific options per mode
Personal throttle protection lock for CAN source or local
Motor temperature limit for charger (DC-DC)

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